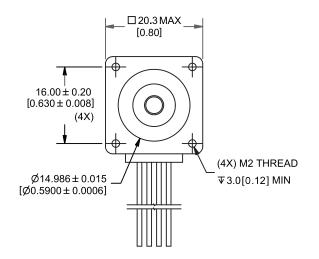
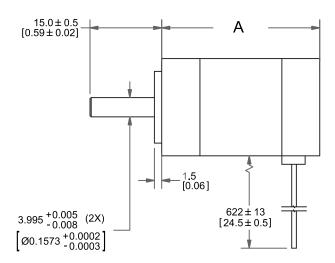




### **DIMENSIONS**

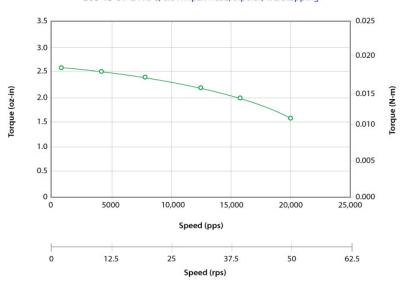


Part Number	W0-208-13-01
Step Angle	1.8°
Frame Size	NEMA 8
Body Length (Dim. A)	1.3 in (33 mm)
Current	0.6 Amps/Phase
Holding Torque	3 oz-in (0.02 Nm)
Resistance	6.5 Ohms/Phase
Rotor Inertia	0.01 oz-in <sup>2</sup>
Number of Leads	4
Connection	Bipolar
Weight	0.13 lbs (0.06 kg)



# **PERFORMANCE CURVE**

**208-13-01** 24VDC, 0.6 Amps/Phase, Bipolar, 1/2 Stepping



#### **OPERATING SPECIFICATIONS**

Radial Play	0.001" max @ 1 lbs load
End Play	0.003" max @ 2 lbs load
Shaft Run Out	0.002" TIR
Concentricity of Mounting Pilot to Shaft	0.003" TIR
Perpendicularity of Shaft to Mounting Face	0.003" TIR
Max Axial Load	0.45 lbs
Maximum Case Temperature	60 C
Ambient Temperature	-20° to 50° C
Storage Temperature	-20° to 100° C
Humidity Range	85% or less, non-condensing
Magnet Wire Insulation	Class B 130° C
Insulation Resistance	100MΩ at 500 VDC
Dielectric Strength	500 VAC for 1 minute

#### **WIRING TABLE**

COLOR	FUNCTION	
Red	A+ Phase	
Blue	A- Phase	
Green	B + Phase	
Black	B- Phase	

## **OPERATION & USAGE TIPS**



Do not disassemble motors; a significant reduction in motor performance will occur.



Do not machine shafts; this will have a negative effect on shaft run out and perpendicularity.



motor from drive while in operation.



Do not use holding torque/detent torque of motor as a fail safe brake.



Do not hold motor by lead wires.



Do not exceed the rated current; this will burn the motor

FAILURE TO COMPLY WITH THESE RECOMMENDATIONS WILL VOID ALL WARRANTY TERMS

#### **RECOMMENDED**



Microstepping Driver



Single Axis Controller + Driver **R256-RO** 

# Motion Control, Solved.

**MOTOR ENGINEERING & MANUFACTURING** 







Small Batch to OEM Volume Production

